Programming - Line Sensor

Summary	Description	Instructor Initial of Completion
Task #1A: Test Line Sensor	Write a program using the command below in which when a white piece of paper is moved in front of it, the right wheel will spin. `line follower Port2▼ leftSide▼ is white▼`	
Task #1B: Test Line Sensor	Write a program using the command below and an Operator so that when a white piece of paper is moved in front of it, the right wheel will spin. `line follower Port2▼ = 3`	
Task#2A: Black Line Triggers Line Sensor	Write a program in which the robot moves forward when the sensor sees black and it does not stop. (Use an Operator.)	
Task#2B: Black Line Triggers Line Sensor / White Stops Motion	Write a program in which the robot moves forward when the sensor sees the black line and stops when the sensor sees white. (Use an Operator.)	
Task #3: Figure 8	Write a program in which the robot moves its way around a Figure 8!	